



**Creator** of global handling solutions

Manufacturer of handling and self-propelled systems

# **Automated Horizontal Transportation 3.0**

Miami 21th of April 2015

#### **Michel Lyrstrand**

Global Sales Director





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The pioneers

**Decoupling** 

The creative mind

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**Buffering** 

**Controlling the fleet** 

Conclusion

No industry would today handle a large amount of unitised cargo without automation.

The automotive industry has used it for decades and so has:

- The food and beverage industries
- Paper and pulp industries
- Steel industries
- Logistic centers
- Airports for their baggage handling
- Seaports for stacking containers

So why isn't automation more frequently used for the transportation between the quay and the stack, also called the "Automated Horizontal Transportation"?





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Even though the question is rather simple, the answer is not as easy. There are several factors that need to be considered, such as:

- CAPEX
- lacksquare OPEX
- Productivity
- Implementation risks.

This presentation will compare existing AGV systems with new technological developments.











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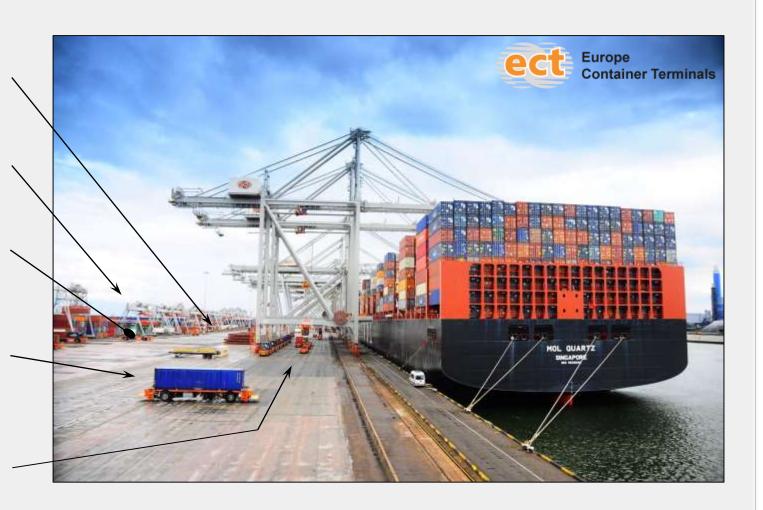
Hatch covers and other handling equipment are mixed with the AGVs

Automated stacking cranes

Sequencing is performed before departure

A mix of
Diesel/Hydraulic
&
Diesel/Electric
"piggy back" AGVs

All container handling is performed within the STS legs





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Hatch covers and other cargo handling equipment are handled within the STS legs

Automated stacking cranes

STS equipped with an automated 2<sup>nd</sup> trolley

Diesel/Electric "piggy back" AGVs

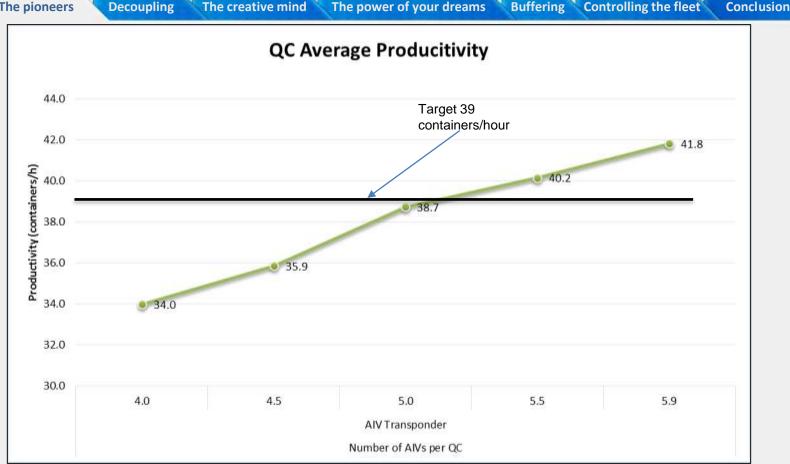
AGV holding lanes for sequencing

All container handling is performed at the STS back-reach









The simulation results show that 5,1 LOLO AIVs per QC will be needed to achieve 39 container moves per hour per QC.

We call this type of application; Version 1.0



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# Decoupling at ASC

#### Traditional layout

- The AGV is waiting for the ASC to be loaded/unloaded
- A "handshake" between the ASC and the AGV is required

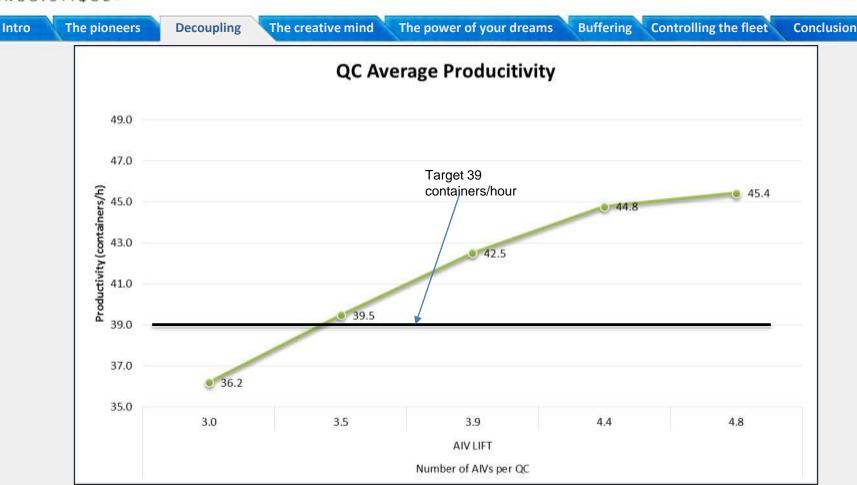


#### Decoupled layout

- Steel racks are used for placing the containers
- A lifting mechanism on top of the AGV is handling the loading/unloading of the containers on the steel racks
- The AGV is no longer waiting for the ASC to be loaded/unloaded
- Less no. of AGVs are needed due to reduced waiting time at the ASC







The simulation results show that 3,5 AIV Lifts per QC will be needed to achieve 39 container moves per hour per QC.

We call this type of application; Version 2.0



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1880 – Eugène GAUSSIN - Metal constructions



1961 - Henri GAUSSIN - Industrial trailers



1970 – Beginning of the containerization



1994 – AIRBUS (FULL ELEC vehicle)



2006 – IPO Listed on the Nyse Alternext



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# Modular design

#### 3 section frame design

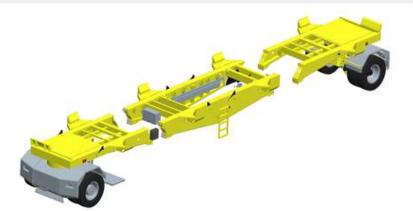
- *All sections are bolted together*
- Reduced welding due to bended plates
- The mid-section has delta-shape design (strength were needed)

#### Axles and drives

- All axels are modular and can be assembled separately
- Two different power sources (Hydraulic or Electric)
- *Hydraulic steering and suspension*

#### **Bolted fittings**

- *All guides and stopper are bolted to the frame*
- Reduced welding due to bolted fittings
- All fittings are easily exchangeable is damage







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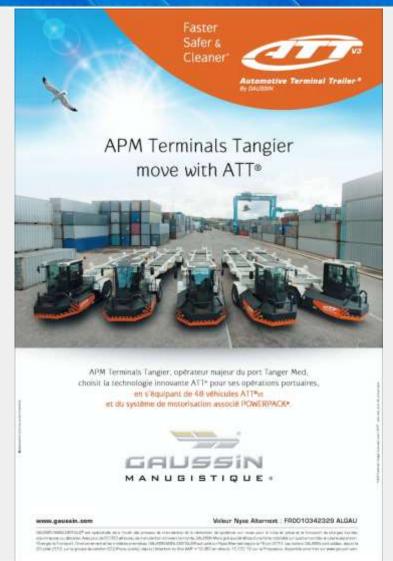
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- On 19 October 2012 APM Terminals Tangier leading operator of the Tanger Med port, confirmed the firm order for 48 ATT V3 vehicles and 51 POWERPACKs.
- After final tests by APM Terminals Tangier undertaken using 9 ATT V3 vehicles from October 2011 to June 2012.
- In addition to the 9 vehicles put at its disposal on the port to carry out the tests, the order included 39 additional ATT vehicles, with delivery planned for the first quarter 2013.
- 51 POWERPACK units, associated motorization systems, were also ordered.





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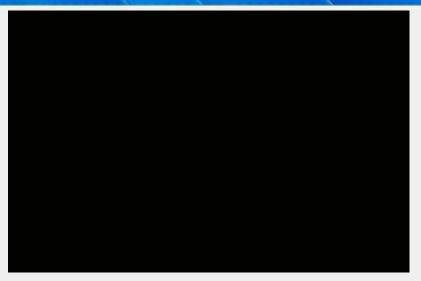
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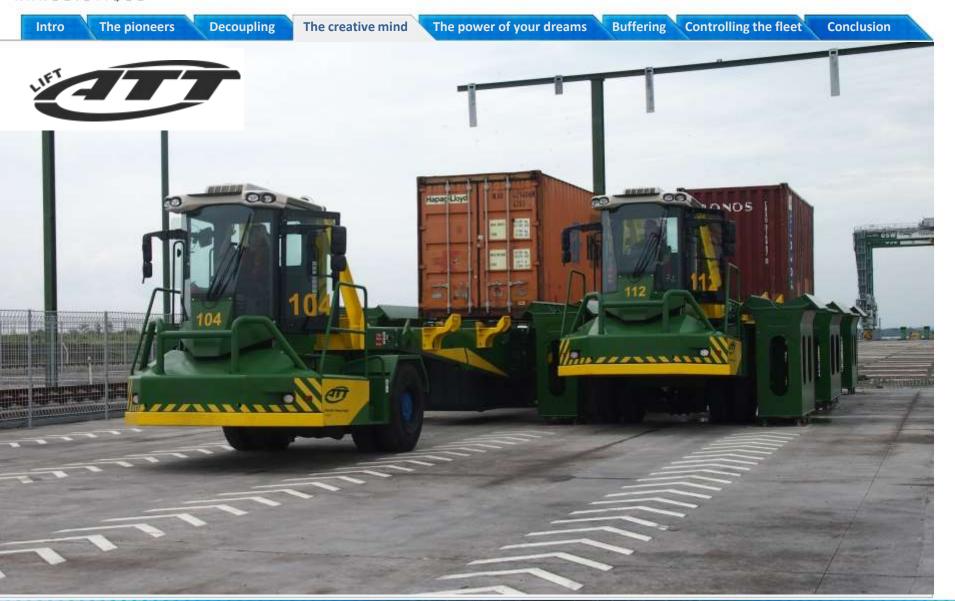














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Decoupling The creative mind The power of your dreams Buffering **Controlling the fleet** The pioneers Conclusion Intro Automotive Intelligent Vehicle® By GAUSSIN



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You just have one vehicle, but would like to change energy source?



Hybrid Diesel/Electric



Full electric **Battery** 



Future energy Full cell-hydrogen

Under development



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# The Power of your dreams...







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Cocooning High performance isolation

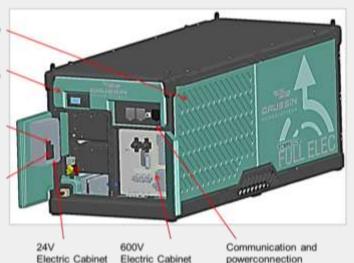
HMI Human Machine Interface

#### ECU

 Power Pack Supervisor + vehicle Interface

#### ECU

Climate control

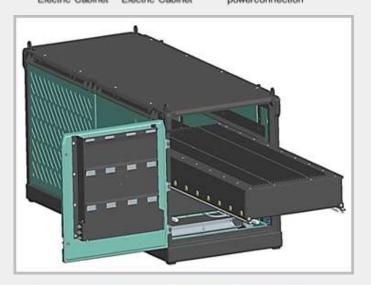


#### Power pack Full electric

Li-ion Battery type:

3 available capacities Energy:

80 kWh, 160kWh or 240kWh. (4h, 8h, 12hours autonomy)





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# The increased manoeuvrability of the AIV





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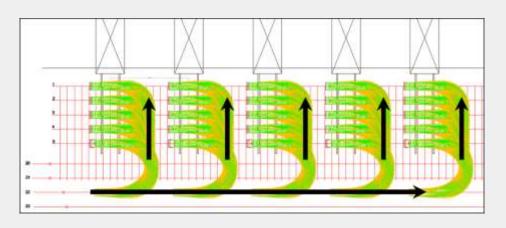
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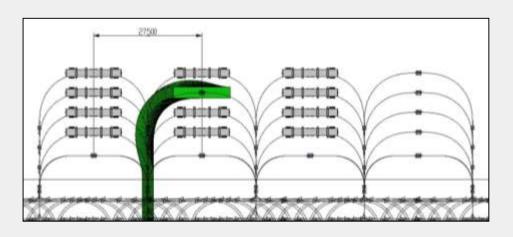
#### New layout with buffering under the QC

Due to the increased manoeuvrability, an AIV can access any transfer point under any QC without any limitation or interference even though the QC are placed "Shoulder to Shoulder"!



The empty AIV can enter/exit the transfer point from any side.

A loaded AIV will need to enter in a specific direction, however a changed door direction is extremely simple to execute since the AIV can enter/exit from any side.





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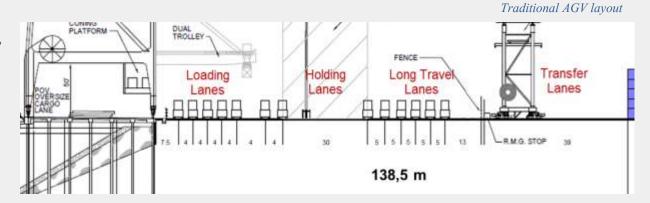
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New AIV layout

#### Sequencing in the buffers

The sequencing of containers performed within buffer under the QC

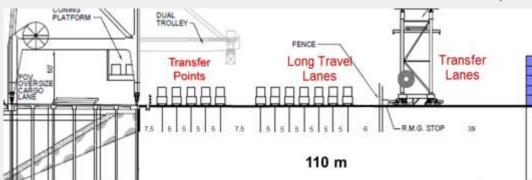


Since the holding lanes are not used anymore, the AIV

operating area can be reduced

with approx. 20%.

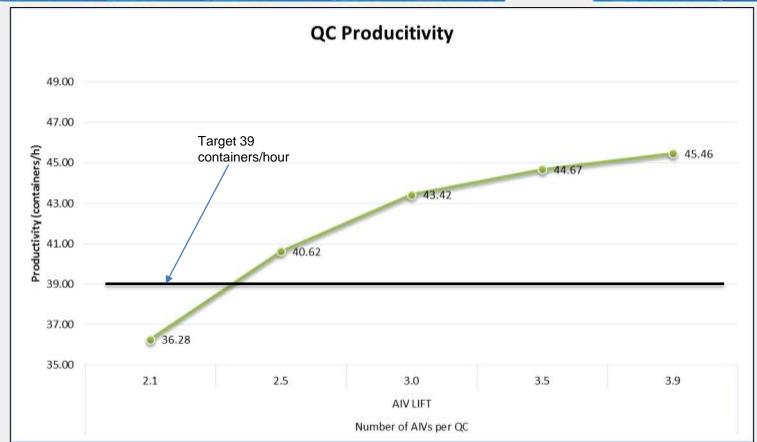
The increased lane width is used to safety enter/exit the transfer points when the QC are place "shoulder to shoulder".



The total saving is 28,5m







The simulation results show that 2,4 AIV Lifts per QC will be needed to achieve 39 container moves per hour per QC.

We call this type of application; Version 3.0



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#### An automated system is never better than the software controlling it!

In October 2014 Gaussin and BA Systemes created the Joint Venture:



BA Systemes long track record, will be the base for Port Automated Systems' success into the automated container handling.



#### **BA SYSTEMES**





#### **BA Systèmes**

- 40 years of experience
- All over Europe
- 250 sites in Europe



#### Two main activities

- Intra Logistics
- Mobile Robotics



Solutions in motion

www.basystemes.com



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#### An automated system is never better than the software controlling it!

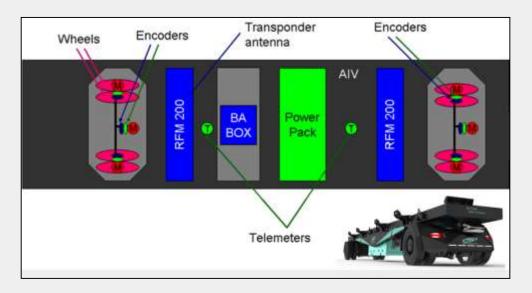
PAS has a well proven Fleet Management System and the interface to TOS and CMS is right now under customization.





PAS has also a full functioning vehicle controller, called the BA-BOX.

The BA-BOX has already an interface to the AIV positing system (navigation) and safety system. The interface to the AIVs lifting-, steering- and drive system is under customization.





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# **CAPEX**

#### The capital cost will decrease when implementing version 3.0 due to:

- Lower amount of vehicles and Power Packs
- Modular and lighter vehicle design to a lower price
- Reduced distance between the ASC and the STS
- Reduced cost for pavement (due to lighter vehicle)
- Lower height of docking station (i.e. simplified foundation)



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# **OPEX**

#### The operating cost will decrease when implementing version 3.0, since:

- The lower amount of vehicles reduces the maintenance cost
- The modularity of Power Packs simplify the maintenance (i.e. cost)
- The lighter vehicle and the reduced traveling distance lower energy consumption
- The lighter vehicle and the reduced traveling distance lower tire cost



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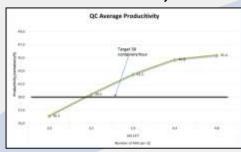
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# **Productivity**

#### Version 2,0



#### Version 3,0



2,4 AIV /QC

#### Version 1,0



5,1 AIV /QC

#### 3,5 AIV /QC

Our simulations have clearly shown that the decoupling and the buffering increases the QC productivity.

What can also be seen from these results, is that the bottleneck is now moved from ATHS to the ASC



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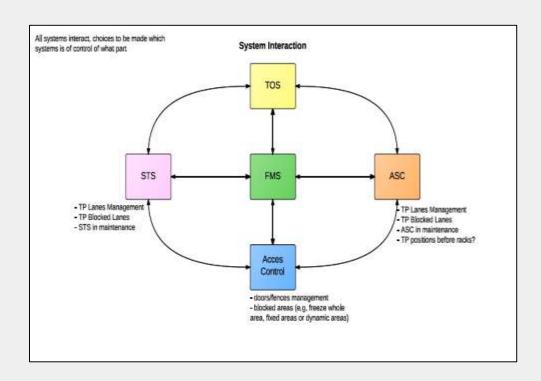
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# Implementation Risk

With over 40 years of experience and 250 automated system in operation, Port Automated System has the correct knowledge when interfacing and building completed systems.

PAS and Gaussin is therefore the reliable partner that has the ability to reduce the implementation risk.





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# Thank you for your attention!

